

# Reprogrammable FPGAs at Astrium

ESA Workshop on Fault-Injection and Fault-Tolerance tools for Reprogrammable FPGAs

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- Application of Reprogrammable FPGAs at Astrium
- Radiation and Single Event Functional Interrupts (SEFIs)
- Determination of SEFI probability
- Some techniques to mitigate SEFIs
  
- DRPM: FPGA Based Generic Module and Dynamic Reconfigurator
  - ESA contract: Astrium (UK) + IDA (Germany)
  - Successful negotiation in May 2009 with KO in June 2009

# Introduction

- Reprogrammable FPGAs are attractive:
  - Flexibility to change programming (algorithm) during development/flight
  - Offer potentially high performance
- At present reprogrammable FPGAs are not used in Astrium flight equipment; instead standard processors (SW), anti-fuse FPGAs and/or custom ASICs are used.  
Reprogrammable FPGAs only used at Astrium in DM and some EMs. ATF280 from Atmel presently being evaluated.
- In the space community reprogrammable FPGAs have generally only been used in non-critical payloads where some data corruption or data loss is accepted by the customer.
- Issues affecting use of reprogrammable FPGAs:
  - Performance: convincing equipment reliability and availability analysis
  - FPGA design and tool set visibility and validation
  - Understanding radiation effects on performance including FPGA state machine.

# Survey: NASA (JPL) Recommendations

- «Assessing and Mitigating Radiation Effects in Xilinx FPGAs»  
JPL Publication 08-9 2/08, NEPP Program  
– very good overview!
- Assessment of mitigation needs:
  - **None: if rate is acceptable and application is NOT critical;**
  - **Detection only: reconfigure upon an upset;**
  - **Full mitigation: design-level Triple Modular Redundancy (TMR) and configuration scrubbing.**
- Mitigation Techniques:
  - **Internal: still requires, at least, an external watchdog timer;**
  - **External: upset-hardened application-specific integrated circuit (ASIC) or one-time programmable (OTP) FPGA.**
- Highly recommended that actual flight designs be subject to radiation testing (TMR (tool) implementation, dynamic effects, ....)

# SEFIs in reprogrammable FPGAs

- SEFI = Single Event Functional Interrupt
  - FPGA device state machine stops or
  - FPGA device state machine continues but output is corrupted.
- 1. Characterise basic radiation performance
  - Static Radiation Characterisation: sensitivity of FPGA architectural elements to heavy ion and proton radiation.
  - Application and Dynamic effects assumed negligible (?)
- 2. Establish relation between SEU and SEFIs
  - Are only SEUs in «used» configuration cells significant?
  - Are SEUs in «unused» configuration cells negligible?
  - Are SEUs in Registers, Block-RAM, User Flip-Flops etc. negligible?
  - What about radiation effects on FPGA device state machine?

# SEFI probability derivation I

## ■ SEFI probability by test (preferred)

- Perform dynamic heavy ion & proton radiation tests on real application under real operational conditions (including mitigation strategies, e.g. TMR) to determine SEFI probability

**BUT** In most cases this approach is compatible with neither the project cost envelope nor the schedule!

# SEFI probability derivation II

- **SEFI probability by analysis (alternative)**
  - If radiation tests not possible, then introduce an appropriate margin (e.g. factor 10) on static radiation data to account for dynamic (temperature?) effects;
  - Derive the SEFI probability as a function of SEU through fault injection (including multiple bit flips) in the real application under real operational dynamic conditions using an appropriate tool;
  - For FPGA elements where fault injection is not feasible then either SEFI originating from these elements must be shown to be negligible (analysis) or an appropriate margin must be taken.
- **Watchdog and Test Pattern Insertion**
  - During operation, SEFI should be monitored by watch dog and regular insertion of a test pattern with high coverage of the design.



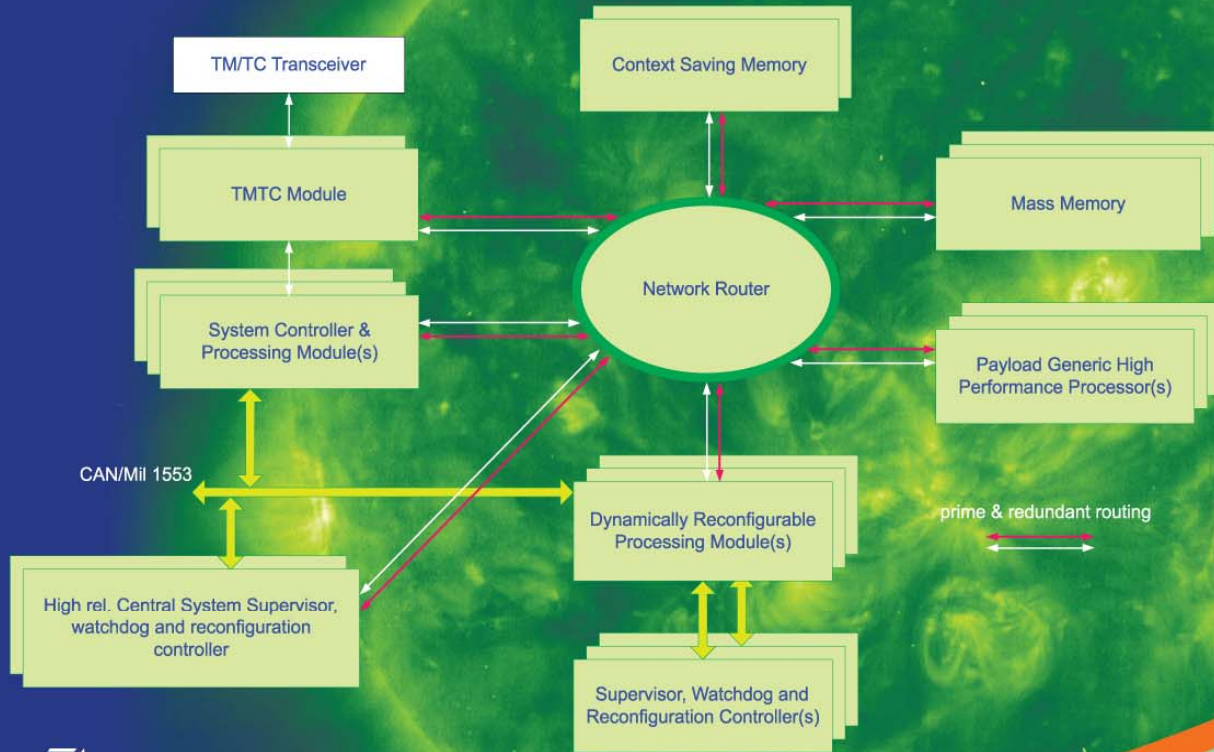
# Some Techniques to Mitigate SEFIs

- Closed loop refresh (scrubbing) of configuration layer?
  - Difficult as dynamic elements must be masked out;
  - Most bit errors in configuration layer will not cause a SEFI;
  - Open loop refresh as much as possible & as often as possible (necessary);
  - Insert Test Pattern with high coverage in data stream.
- Triple Modular Redundancy (TMR)?
  - Yes, but TMR implementation (tool) must be validated;
  - Dual path (TMR?) at component level;
  - Buffer data with FPGA refresh & retry if SEFI.



# FPGA Based Generic Module and Dynamic Reconfigurator

ITT AO/1-5969/08/NL/LvH



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# DRPM Project Objectives

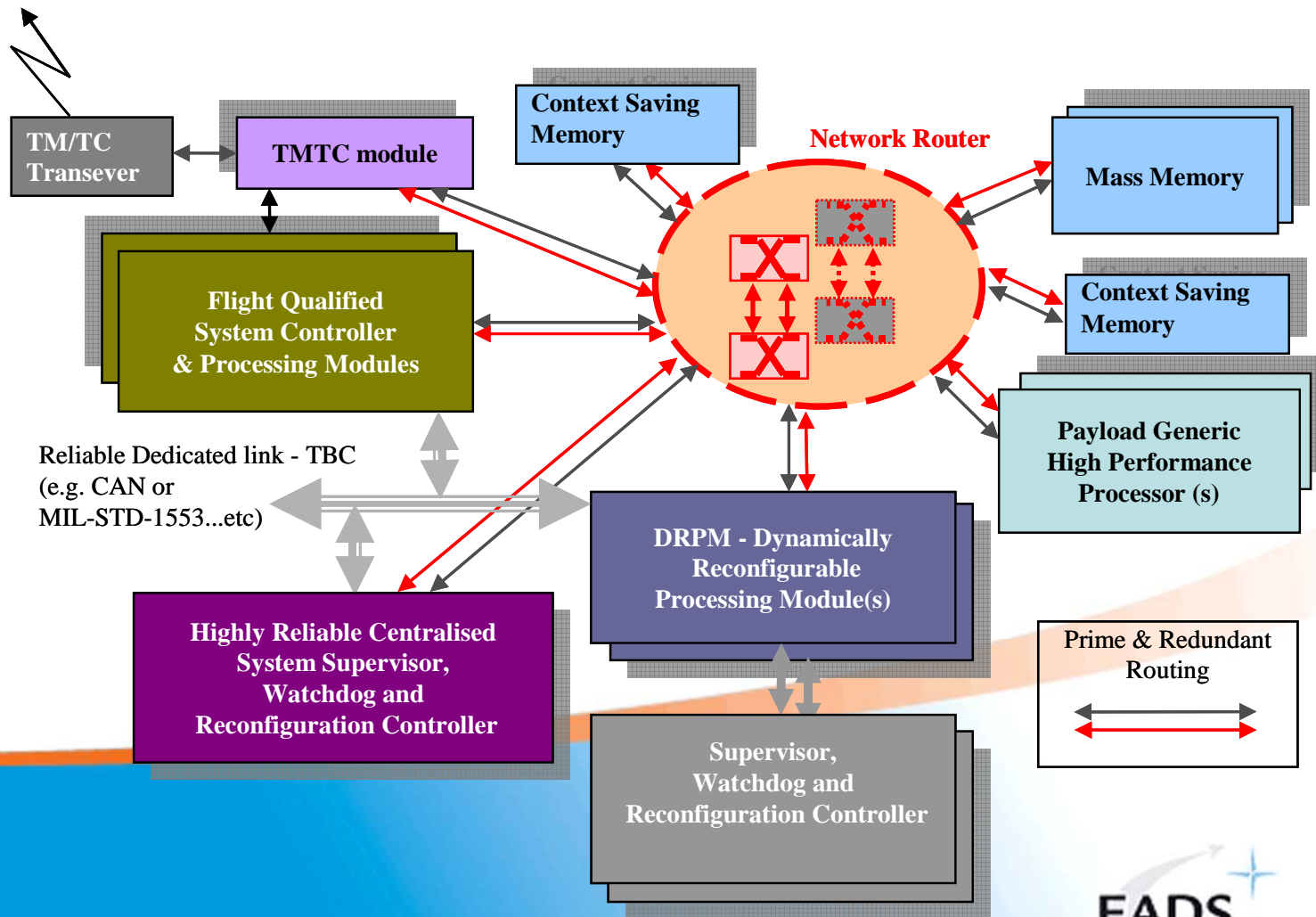
- Project aims to develop a demonstrator of an in-flight reconfigurable processing platform for primary use in missions demanding hardware re-usability and design flexibility.
- Deliver a development flow and validation methodology for application design and deployment.

## Aim to satisfy the following broad requirements:

- **Versatile processing and interfacing** catering for multi-instrument payloads
  - ✓ Modular and Scalable solution
- Provide a **reusable processor** for cost effectiveness
  - ✓ Mission and/or In-flight reprogramming
- Improve processing module **reliability** despite sensitivities of reconfigurable technology in radiation environments
- Provide roadmap to **flight solution**, enabled by appropriate technology selection and **application development methodology**



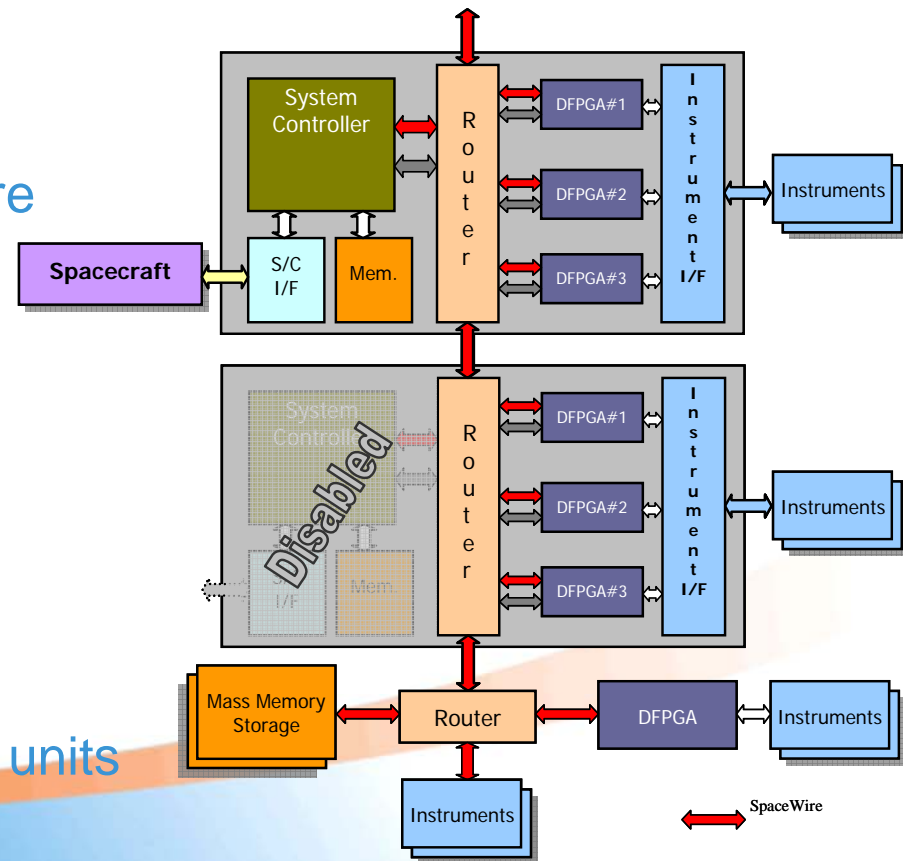
# DRPM Concept



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# DRPM Modularity and Scalability

- Router provides backbone for interconnection between DRPMs
- System controller can handle more than one DRPM
- DFPGA modules provide in-flight reconfiguration and ultimately application programming
- Network interfaces can provide system controller and DFPGAs accessibility to a number of Instruments and memory storage units



# Demonstrator Design Drivers

## ■ Technology Drivers

- **Reconfigurable Core**
  - ability to reconfigure the devices and provide as much flexibility, reliability and efficiency in achieving this
  - the provision of enough reconfigurable resources for handling the processing requirements
  - Technology supported by tools, enabling application development
- **Reconfigurable Core Supervisor and Controller**
  - Device capable of supporting required processing requirements (e.g. size, maximum interface speed)
  - Technology selected based on reliability offered by space qualified counterpart
- **System Controller**
  - sufficient computing power
  - software driven for solution flexibility
  - high radiation tolerance and overall reliability
- **Interfaces**
  - Limitations of IO rates and electrical requirements of aforementioned units, instrumentation and control interfaces



# Application Development Environment (1)

- The aim is to reduce the difficulty in managing dynamically reconfigured applications and to provide a reliable implementation, by providing tools and associated methodologies addressing the following issues:
  - Automatic or manual **partitioning** of a conventional design
  - Specification of the dynamic **constraints**
  - **Verification** of the dynamic implementation through dynamic simulations at key steps of the design flow
  - **Development of configuration controller** core
  - Dynamic **floorplanning management** and guidelines for modular back-end implementation if not supported easily by vendor tools.

# Application Development Environment (2)

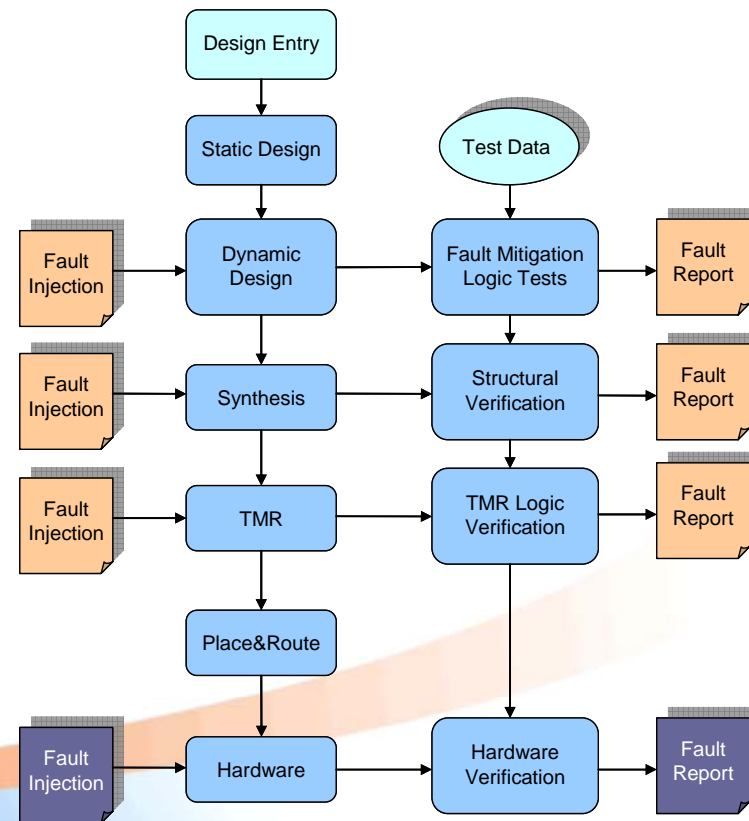
- In support of the application development and validation, it is necessary to provide the user with a design tool kit and methodology
- Considerations are :
  - the **technology of the reconfigurable elements** used within the DRPM;
  - a design containing microprocessors, thus requiring a **software and hardware development thread**; i.e. co-development issues;
  - the **validation strategy**, which must allow for the incremental testing of applications as part of the wider DRPM processor.



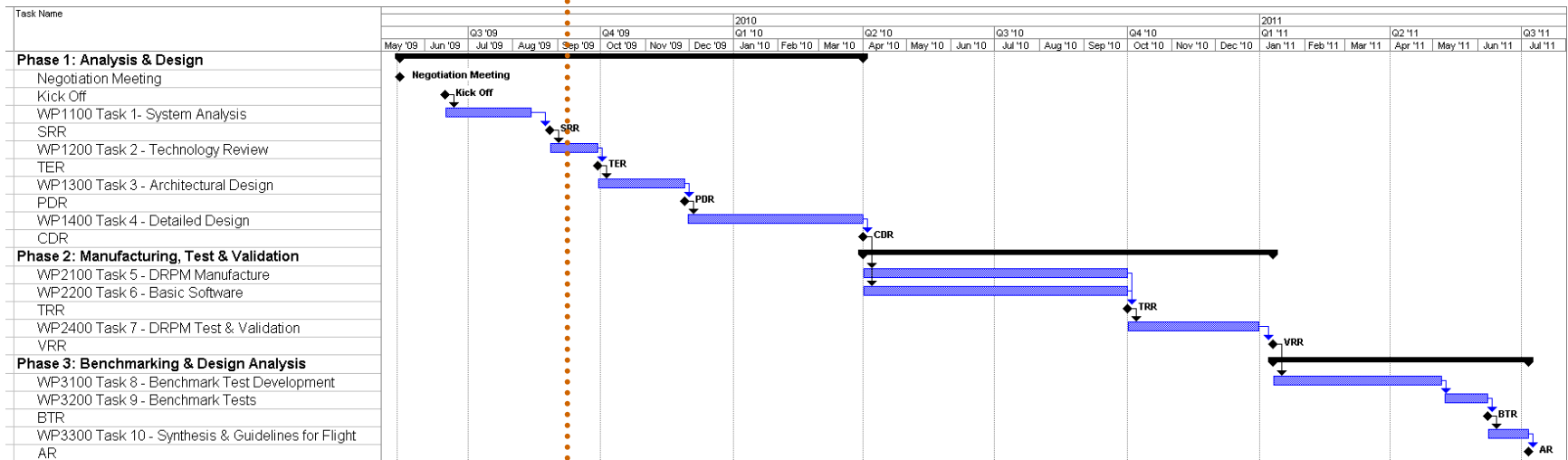
# Fault Testing

## Fault Injection for testing effectiveness of:

- Triple Modular Redundancy;
- configuration memory scrubbing;
- applying EDAC or CRCs where necessary (e.g. memory data, data path processing etc.);
- using partial reconfiguration for correcting faulty configuration or user memory data;
- automatic or semi-automatic switching out of faulty units or system elements (e.g. system controllers, DFPGA modules, DRPM modules, interfaces etc.);
- re-distributing application functionality from faulty reconfigurable cores in the event of partial failure of reconfigurable core fabric;



# Dates of Delivery and Progress Milestones



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